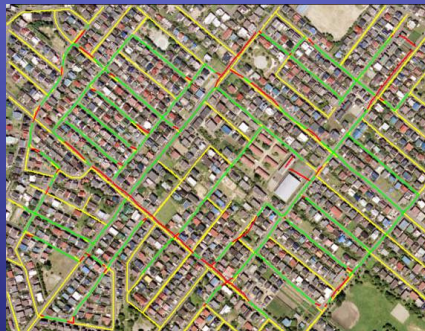
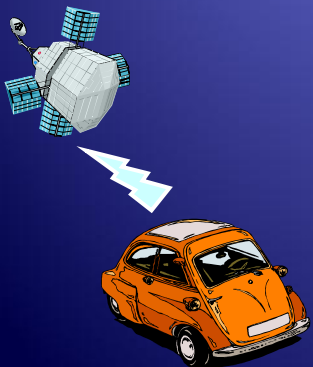


# **Kickoff Meeting of ICT-PAMM**

**ITS Lab in Kumamoto University, Japan**

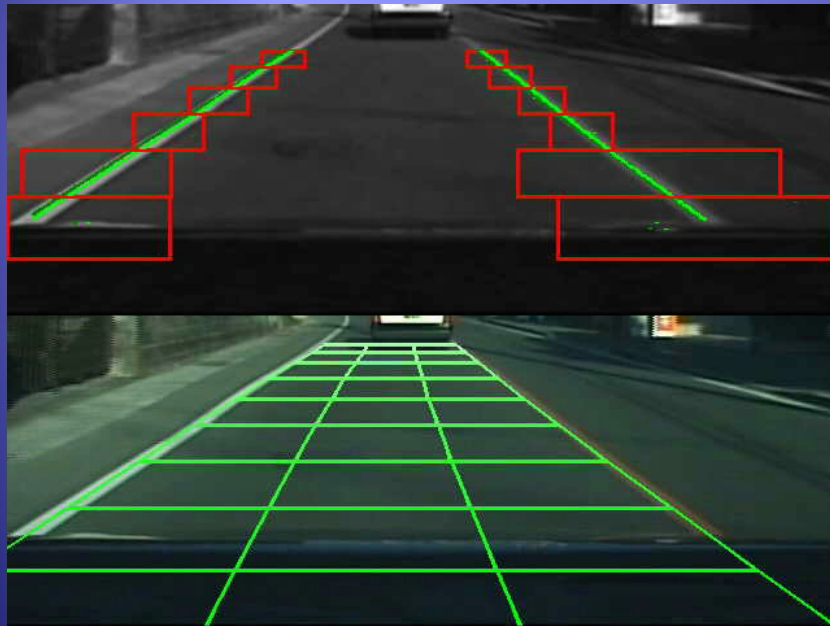
# Our Lab: ITS Research Lab

- More than 20 members working on Computer vision based ITS applications
  - Sensing and perception technology for Adaptive Driving Assistance System (ADAS)
  - Driver inattention monitoring system
  - In-vehicle Navigation with new HMI
  - Parking Assistance System
  - Personal EV: new mobility for the elder society
  - Satellite image processing for digital map



Visit us at <http://navi.cs.kumamoto-u.ac.jp>

# Sensing and Perception

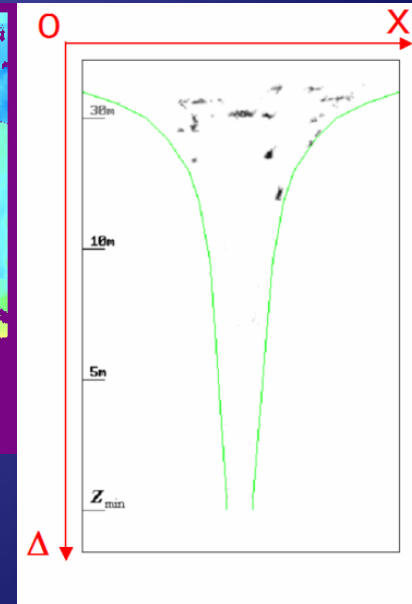
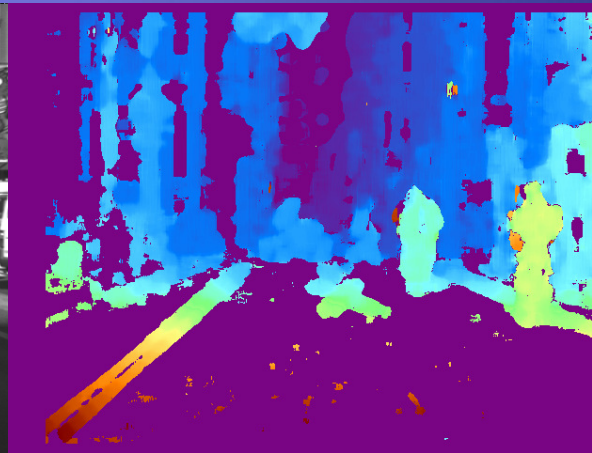
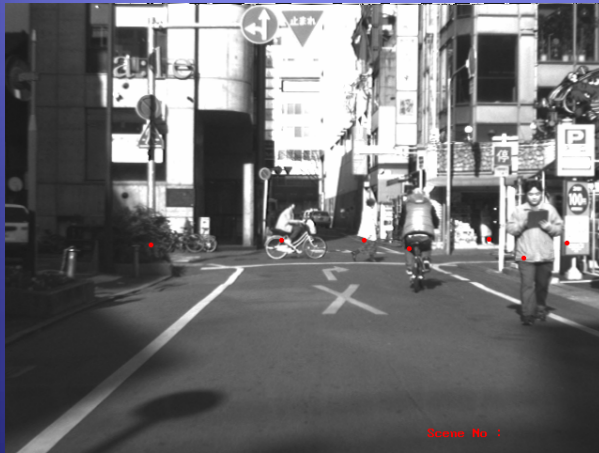


**Night**

Lane detection under extremely difficult conditions

# Sensor Fusion on Road

- ◆ Stereo vision, Laser radar based Obstacle Detection System for Full Speed Range ACC



# Parking Assistance System (PAS)

- ◆ Surrounding view and sonar array based PAS



# Direct Visual Navigation

- ◆ Direct visual information superimposed onto real scene
- ◆ Need precise camera registration and HMI technology

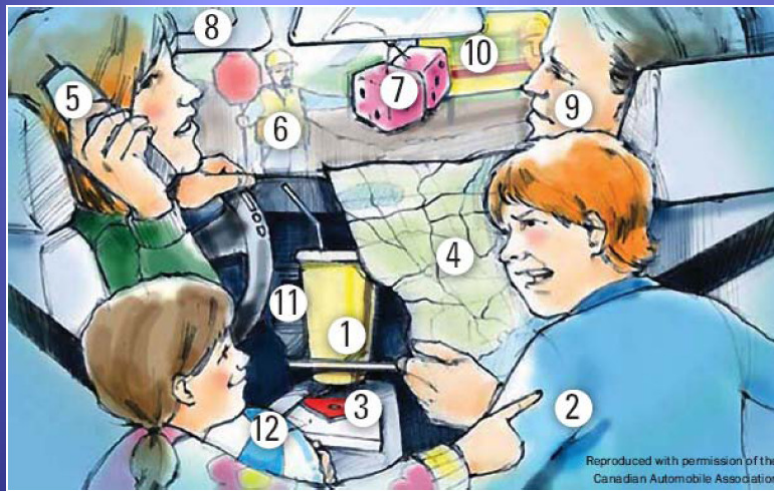


# Contributing to ICT-PAMM

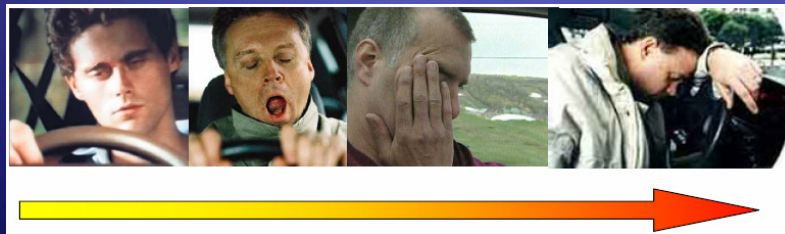
- ◆ Human centered HMI for new mobile robots
- ◆ A practical platform for mobile robots
- ◆ Sensing and perception for mobile robots

# Driver Inattention Monitoring

Driver Distraction:



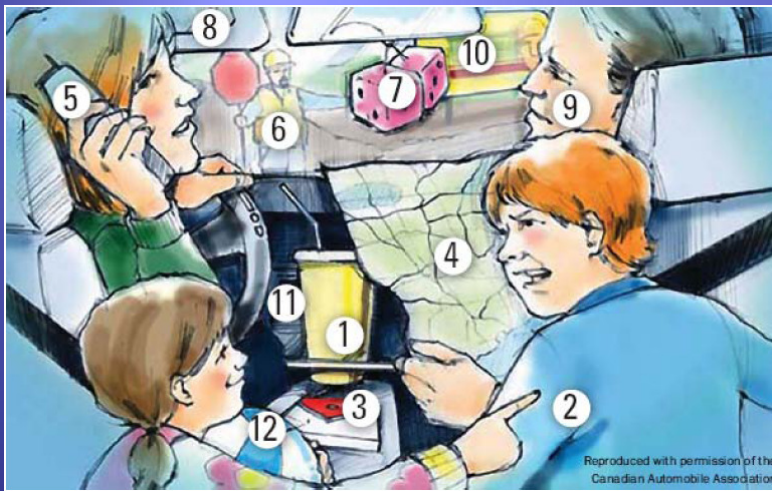
Driver Fatigue:



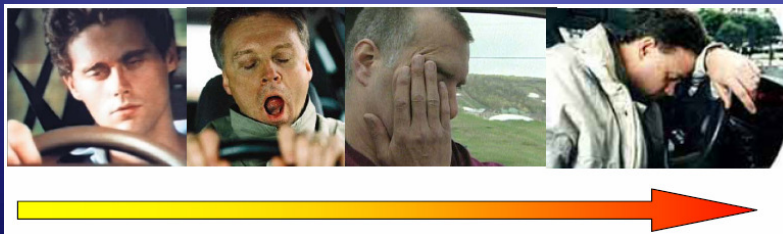


# Driver Inattention Monitoring

## Driver Distraction:

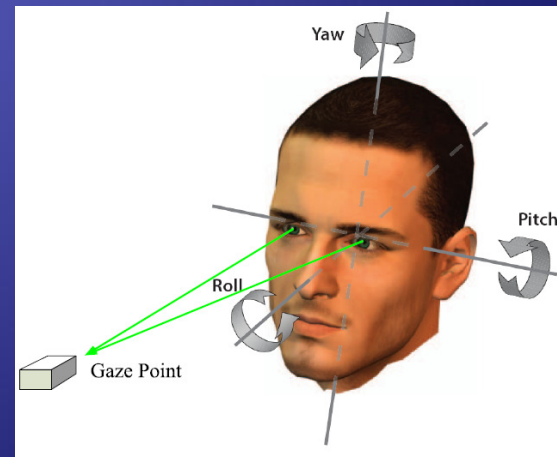


## Driver Fatigue:



## Functional Requirements

- Face Position Estimation
- Face Orientation Estimation
- Face Expression Estimation
- Gaze Estimation



# Main Categories

## *Biological signal processing*



EEG

EOG

ECG

sEMG

## *Behaviour analysis*



Seat pressure  
(**SP**)

Steering  
angle (**SA**)

Pedal signal  
(**PS**)

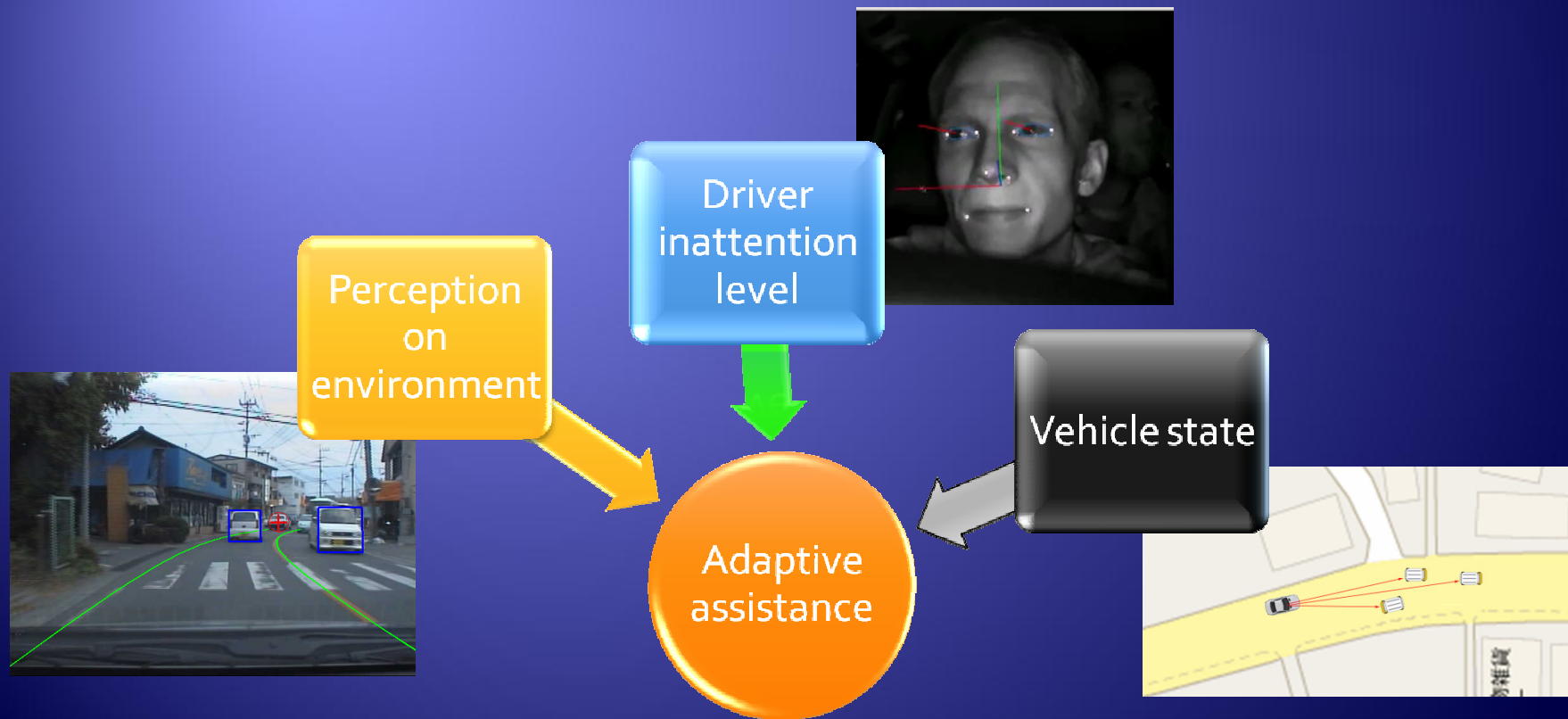
Lane position  
(**LP**)

## *Image processing*



# Human centered HMI

- A comprehensive approach links between environmental perception result and driver inattention level with vehicle states to deliver adaptive assistance to human driver for ADAS



# Building a platform: STAVi



# Sensing Ability of STAVi



# Sensing and perception

- ❑ Lidar / visual SLAM
- ❑ Pedestrian and obstacle detection and avoidance
- ❑ Indoor localization and navigation
- ❑ Comprehensive risk analysis

# Welcome to Kumamoto, Japan for 2012 annual meeting of ICT-PAMM!



# Access to Kumamoto



## From Fukuoka

- 110 km
- about 40 mins by Shinkansen  
(high speed train)

## From Tokyo

- 20 flights daily
- about 1.5 hours flight
- about 6 hours by Shinkansen  
(high speed train)

## From Osaka

- 20 flights daily
- about 1 hours flight
- about 4 hours by Shinkansen  
(high speed train)



# Best season in Kumamoto



Spring



Autumn

**THANK YOU!**